

113 學年度科技校院四年制與專科學校二年制

統一入學測驗公告答案

考科代碼：4-01-1

類 別：機械群

考 科：專業科目(一)機件原理、機械力學

| 題號 | 答案 | 題號 | 答案 | 題號 | 答案 | 題號 | 答案 | 題號 | 答案 | 題號 | 答案 |
|----|----|----|----|----|----|----|----|----|----|----|----|
| 1 | B | 11 | A | 21 | A | 31 | B | 41 | | 51 | |
| 2 | B | 12 | D | 22 | A | 32 | A | 42 | | 52 | |
| 3 | D | 13 | D | 23 | D | 33 | D | 43 | | 53 | |
| 4 | C | 14 | C | 24 | D | 34 | A | 44 | | 54 | |
| 5 | D | 15 | A | 25 | B | 35 | C | 45 | | 55 | |
| 6 | B | 16 | B | 26 | C | 36 | B | 46 | | 56 | |
| 7 | A | 17 | C | 27 | B | 37 | D | 47 | | 57 | |
| 8 | C | 18 | C | 28 | B | 38 | C | 48 | | 58 | |
| 9 | B | 19 | A | 29 | A | 39 | D | 49 | | 59 | |
| 10 | A | 20 | B | 30 | D | 40 | C | 50 | | 60 | |

1. (B) ∵ $P = \frac{3}{2}N - 2$ 為拘束運動鏈，當 $N = 4$ ， $P = 4$ 則 $P = \frac{3}{2}N - 2$ 成立

當 $N = 4 + 2 = 6$ ， $P = 4 + 3 = 7$ 則 $P = \frac{3}{2}N - 2$

當 $N = 6 + 2 = 8$ ， $P = 7 + 3 = 10$ 則 $P = \frac{3}{2}N - 2 \dots\dots$

即連桿數目 N 從 4 件開始設計，每增加 2 件連桿數，則其對偶數 P 增加 3 個均為拘束運動鏈。

2. (B) (1) 差動螺旋導程 $L = L_1 - L_2 = 5 - 3 = 2(\text{mm})$

$$(2) \because F \times 2\pi R \times 1 = W \times L \Rightarrow R = \frac{4000 \times 2}{10 \times 2\pi \times 1} = \frac{400}{\pi} (\text{mm})$$

3. (D) 螺帽下方加裝一螺旋彈簧墊圈，此鎖緊裝置歸類為：摩擦鎖緊裝置。

4. (C) 錐形彈簧壓縮時，小圈部分變形較小並縮進大圈內。

(1) 彈簧支持負載時，能有效伸縮之圈數稱為有效圈數；

(2) 螺旋彈簧之彈簧指數愈小，則表示彈簧愈不容易變形；

(3) 蝸旋扭轉(動力)彈簧可使鑽床進刀把手在鑽完孔後能自動回彈。

5. (D) 對合式滑動軸承又稱剖面滑動軸承，可承受較大負載與衝擊，磨損時可調整且安裝拆卸方便。

6. (B) 360 rpm。

$$(1) \because n_{\text{低}} = \frac{1}{4} n_{\text{高}} ;$$

$$(2) \because (N_{\text{主}})^2 = n_{\text{高}} \times n_{\text{低}} = \frac{1}{4} (n_{\text{高}})^2 \Rightarrow n_{\text{高}} = \sqrt{4 \times (180)^2} = 360(\text{rpm})$$

7. (A) 兩個鏈輪的節圓直徑與轉速比成反比為 1 : 4。

8. (C) $\sqrt{2}$ °

$$\because 75^\circ = 45^\circ + \beta \Rightarrow \beta = 30^\circ$$

$$\therefore \frac{N_B}{N_A} = \frac{\sin \alpha}{\sin \beta} = \frac{\sin 45^\circ}{\sin 30^\circ} = \sqrt{2}$$

9. (B) 160rpm °

$$(1) \because i_{\max} = \frac{N_A}{N_B} = \frac{D_B}{D_A} = \frac{16}{8} = \frac{2}{1} \Rightarrow N_{B(\min)} = \frac{1}{2} \times 100 = 50(\text{rpm})$$

$$(2) \because i_{\min} = \frac{N_A}{N_B} = \frac{D_B}{D_A} = \frac{8}{16} = \frac{1}{2} \Rightarrow N_{B(\max)} = 2 \times 100 = 200(\text{rpm})$$

$$(3) \Rightarrow N_B = 50(\text{rpm}) \sim 200(\text{rpm})$$

10. (A) 300rpm °

$$(1) \because C = \frac{M(T_A + T_B)}{2} \Rightarrow 200 = \frac{5(20 + T_B)}{2} \Rightarrow T_B = 60 \text{ 齿}$$

$$(2) \because N_A = \frac{T_B}{T_A} \times N_B = \frac{60}{20} \times 100 = 300(\text{rpm})$$

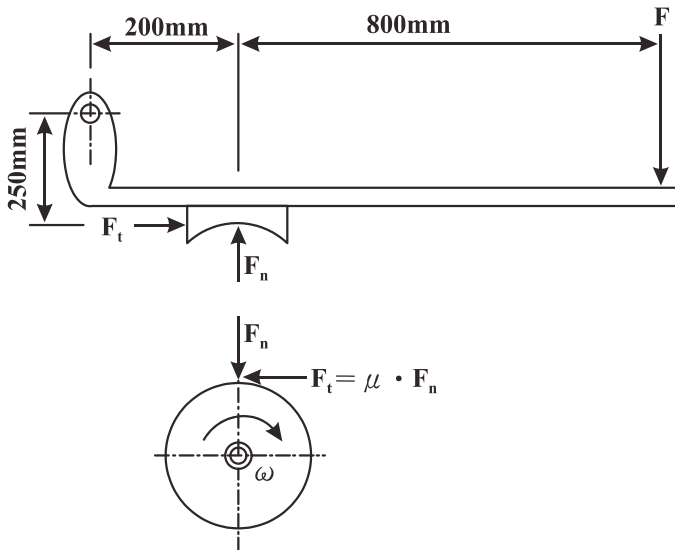
11. (A) 1.6π (kW) °

$$(1) \because \Sigma M_o = 0$$

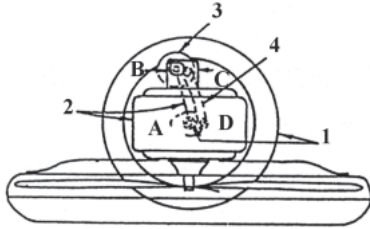
$$\Rightarrow F_t \times 250 + F_n \times 200 - 1000 \times (200 + 800) = 0$$

$$\Rightarrow F_t = \frac{1000 \times 1000}{250 + \frac{200}{0.2}} = 800(\text{N})$$

$$(2) \because \underline{P} = F_t \times \pi DN = \frac{800}{1000} \times \pi \times \frac{200}{1000} \times \frac{600}{60} = 1.6\pi(\text{kW})$$



12. (D)風扇搖擺頭屬於雙搖桿機構。

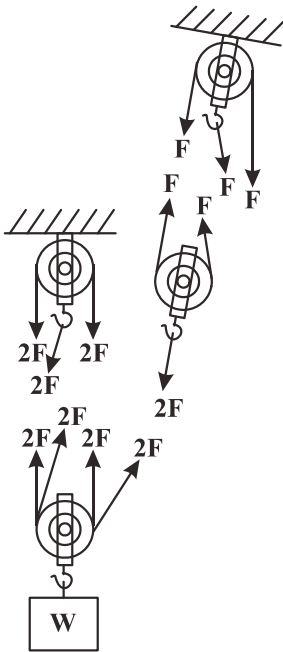


風扇搖擺頭

13. (D)簡諧運動。蘇格蘭軛機構屬於雙滑塊連桿機構應用，為簡諧運動模擬機構。

14. (C)等徑凸輪屬於確動型凸輪。

15. (A)150(N)。∵ $W=8F \Rightarrow F=\frac{W}{8}=\frac{1200}{8}=150(N)$



16. (B)3 秒。∵ $t=\frac{18}{6}=3$ 秒

17. (C) $600/\pi$ (rpm)。

$$(1) \because V = \pi D N_B \Rightarrow N_B = \frac{200}{\pi \times 1} = \frac{200}{\pi} \text{ (rpm)}$$

$$(2) \because \frac{N_A}{N_B} = \frac{T_B}{T_A} = \frac{3}{1} \Rightarrow N_A = 3 \times \left(\frac{200}{\pi} \right) = \frac{600}{\pi} \text{ (rpm)}$$

18. (C)蒸汽火車的動力產生與傳遞，使用多組汽缸與活塞，當某一個活塞正位於汽缸的死點位置時，其他汽缸推動活塞產生動力克服了死點位置。

19. (A) 15ω 。

(1) $\because N_B = N_C$

$$\Rightarrow e_{C/G} = \frac{N_G}{N_C} = \frac{32 \times 1}{16 \times 60} = \frac{1}{30}$$

$$\Rightarrow N_C = 30 \times \omega = 30\omega = N_B$$

(2) $\because e_{B/A} = \frac{N_A}{N_B} = \frac{T_B}{T_A} = \frac{20}{40} = \frac{1}{2}$

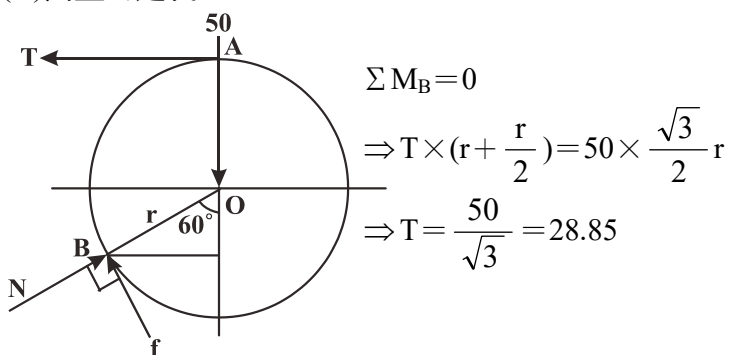
$$\Rightarrow N_A = \frac{1}{2} \times N_B = \frac{1}{2} \times (30\omega) = 15\omega$$

20. (B) 4。

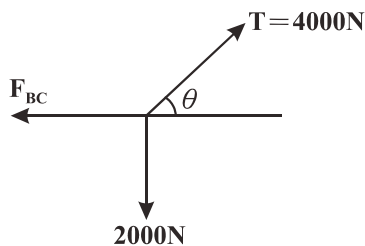
$$\therefore \frac{\sigma_C}{\tau} = \frac{\frac{4T}{D \times H \times L}}{\frac{2T}{D \times W \times L}} = \frac{2W}{H} = \frac{2 \times 12}{6} = 4$$

21. (A) 向量的定義。

22.



23.



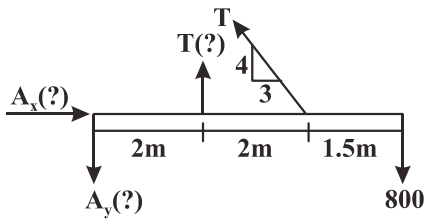
(1) $\Sigma F_y = 0 \Rightarrow 4000 \sin \theta - 2000 = 0$

$$\Rightarrow \sin \theta = \frac{1}{2} \Rightarrow \theta = 30^\circ$$

$$\therefore y = 1.5 \sin 30^\circ = 0.75$$

(2) $\Sigma F_x = 0 \Rightarrow F_{BC} = 4000 \times \frac{\sqrt{3}}{2} = 2000\sqrt{3} = 3464$

24.



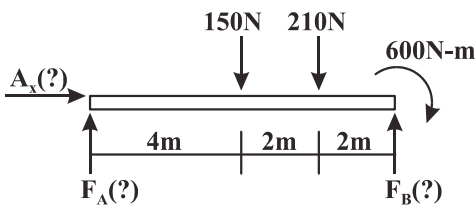
$$(1) \sum M_A = 0 \Rightarrow T \times 2 + \frac{4}{5} T \times 4 - 800 \times 5.5 = 0 \Rightarrow T = 846$$

$$(2) \sum F_x = 0 \Rightarrow A_x - \frac{3}{5} T = 0 \Rightarrow A_x = 507$$

$$(3) \sum F_y = 0 \Rightarrow A_y - T - \frac{4}{5} T + 800 = 0 \Rightarrow A_y = 723$$

$$\therefore R_A = \sqrt{507^2 + 723^2} = 883$$

25.

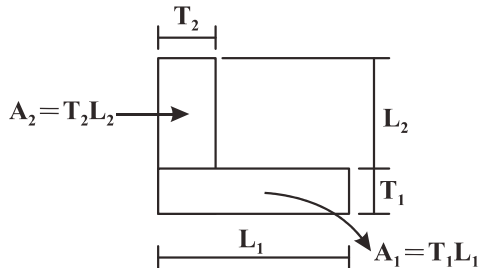


$$(1) \sum M_A = 0 \Rightarrow F_B \times 8 - 150 \times 4 - 210 \times 6 - 600 = 0$$

$$\Rightarrow F_B = 307.5$$

$$(2) \sum F_y = 0 \Rightarrow F_A = 150 + 210 - 307.5 = 52.5$$

26.



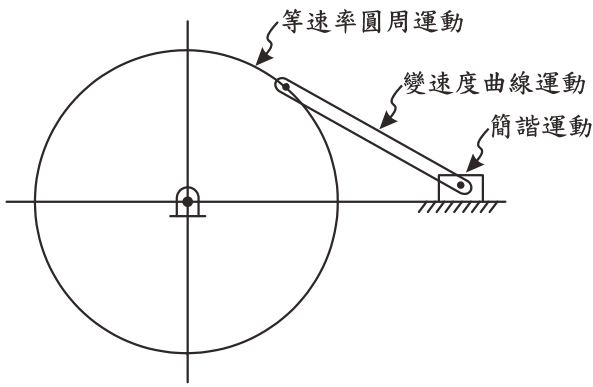
$$(1) \bar{x} A = \sum A_i x_i$$

$$\Rightarrow \bar{x} = \frac{T_1 L_1 \times \frac{L_1}{2} + T_2 L_2 \times \frac{T_2}{2}}{T_1 L_1 + T_2 L_2}$$

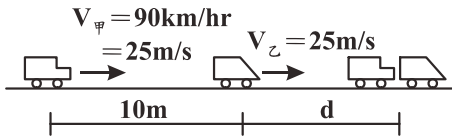
$$(2) \bar{y} A = \sum A_i y_i$$

$$\Rightarrow \bar{y} = \frac{T_1 L_1 \times \frac{T_1}{2} + T_2 L_2 \left(\frac{L_2}{2} + T_1 \right)}{T_1 L_1 + T_2 L_2}$$

27.



28.



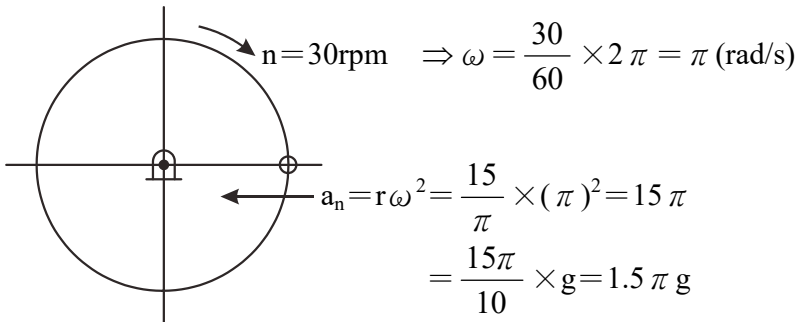
$$S = V_1 t + \frac{1}{2} a t^2$$

$$\text{甲} \Rightarrow 10 + d = 25t + \frac{1}{2} \times 5 \times t^2 \dots\dots (1)$$

$$\text{乙} \Rightarrow d = 25t \dots\dots (2)$$

$$(2) \text{代入}(1) \Rightarrow 10 = \frac{1}{2} \times 5 \times t^2 \Rightarrow t = 2 \text{ 秒}$$

29.



30. (1) $F_1 - 7500 = 750 \times 1 \Rightarrow F_1 = 8250 \text{ N}$

(2) $2500 - F_2 = 250 \times 1 \Rightarrow F_2 = 2250 \text{ N}$

(3) $T = (F_1 - F_2) \times r = (8250 - 2250) \times 0.3 = 1800 \text{ (N-m)}$

31. (B) 光滑面僅會滑動且最快。

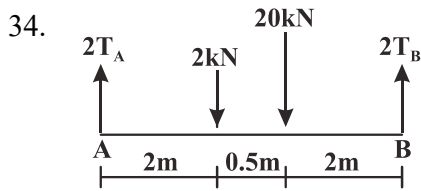
32. (1) $\frac{1}{2} mV^2 = \frac{1}{2} \times 0.5 \times 1^2 = 0.25 \text{ (N-m)}$

(2) $0.25 \times 0.81 = 0.2025 \text{ (N-m)}$

(3) $\frac{1}{2} kx^2 = \frac{1}{2} \times 450 \times x^2 = 0.2025$

$\Rightarrow x = 0.03 \text{ m} = 30 \text{ (mm)}$

33. (D)在比例限内 $\Rightarrow \mu = \left| \frac{\epsilon_{\text{横}}}{\epsilon_{\text{纵}}} \right|$



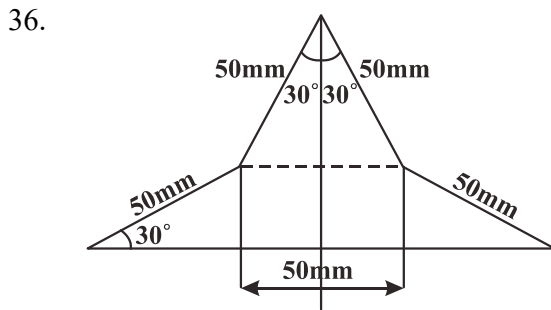
(1) $\sum M_B = 0 \Rightarrow 2T_A \times 4.5 - 2 \times 2.5 - 20 \times 2 = 0 \Rightarrow T_A = 5\text{kN}$

(2) $\sum F_y = 0 \Rightarrow 2T_A + 2T_B - 2 - 20 = 0 \Rightarrow T_B = 6\text{kN}$

(3) $\delta = \frac{PL}{EA} = \frac{5000 \times 2000}{(200 \times 10^3) \times 100} = 0.5\text{mm}$

35. $n = \frac{\sigma_{yp}}{\sigma} \Rightarrow 3 = \frac{360}{\sigma} \Rightarrow \sigma = 120(\text{MPa})$

$A = \frac{P}{\sigma} = \frac{6000}{120} = 50(\text{mm}^2)$



$F = \tau \times A = 300 \times 3 \times (50 \times 8) = 360000(\text{N}) = 360(\text{kN})$

37. $I = \frac{bh^3}{12} \Rightarrow 2 \times 2^3 = 16$

38. (1) $\bar{y}A = \sum A_i y_i \Rightarrow \bar{y} = \frac{20 \times 5 + 20 \times 11}{20 + 20} = 8$

(2) $\sigma = \frac{M_y}{I} \Rightarrow \frac{\sigma_t}{\sigma_c} = \frac{8}{4} = 2$

40. $\phi_A = \frac{TL}{GJ} = \frac{32TL}{G\pi d^4}$

$\phi_B = \frac{T \times \frac{L}{2}}{G \times \frac{\pi d^4}{32}} + \frac{T \times \frac{L}{2}}{G \times \frac{\pi}{32} [d^4 - (\frac{d}{2})^4]} = \frac{32TL}{G\pi d^4} \times \frac{31}{30}$